Small Business Innovation Research/Small Business Tech Transfer

Vacuum-Compatible Multi-Axis Manipulator/Machining Center for Long-Duration Space Missions, Phase II



Completed Technology Project (2008 - 2010)

Project Introduction

NASA has many needs for maintenance and repair technologies for long-duration human space missions. We propose to continue developing a compact, portable, vacuum-compatible, multi-axis Manipulator/Machining Center (M/MC) to satisfy many of NASA's needs. Our M/MC will provide complex manipulation during: layer-additive manufacturing; collection of geometric data for reverse-engineering; real-time non-destructive evaluation; and non-destructive material property determination. Our M/MC will also finish-machine near-net-shape parts produced using layer-additive manufacturing. Design features of our M/MC will: minimize mass, volume, and power consumption while providing required capabilities; maximize life and reliability; and enable our M/MC to operate in space-based vacuum, microgravity, and partial-gravity environments. In Phase II, we will: generate alternative designs of M/MCs for space-based applications; and design, build, test, and zero-g-flight-test a prototype M/MC. In Phase III, we will design, build, and sell M/MCs to the government and private sector.

Primary U.S. Work Locations and Key Partners



Organizations Performing Work	Role	Туре	Location
	Lead Organization	NASA Center	Houston, Texas
Beck Engineering, Inc.	Supporting Organization	Industry	Port Orchard, Washington



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Organizational Responsibility

Responsible Mission Directorate:

Space Technology Mission Directorate (STMD)

Lead Center / Facility:

Johnson Space Center (JSC)

Responsible Program:

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Primary U.S. Work Locations		
Texas	Washington	

Project Transitions

June 2008: Project Start

June 2010: Closed out

Project Management

Program Director:

Jason L Kessler

Program Manager:

Carlos Torrez

Technology Areas

Primary:

 TX12 Materials, Structures, Mechanical Systems, and Manufacturing
 TX12.4 Manufacturing

└─ TX12.4.5
 Nondestructive
 Evaluation and Sensors

